

T-4

Presentation
to the
Land Working Group
of the
MODIS Science Team
from
MCST (MODIS Characterization Support Team)

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1615 Tuesday, 14 April 1992

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Attachment 4.1

Overview of Part 1

of

MCST Presentation to Land Working Group

Land-Related MODIS Geometric Requirements

MODIS Pointing Knowledge Requirement Memo

Salomonson and Barker Georeferencing Talk

MCST Simulated Band-to-Band Sensitivity

Mis-Registered Full-Scene Histograms

MCST Simulated Scene/Pointing Sensitivity

MODIS Pointing Knowledge Requirements

MODIS Pointing Knowledge Goals

Back-Up Charts on Geometric Requirments

Definitions Related to Geometric Requirements

Error Budget from SBRC

Band-to-Band

Pointing Knowledge

Salomonson and Barker Georeferencing Text

MODIS Pointing Knowledge Requirement Memo

Posted: Mon, Mar 23, 1992 10:33 AM EST

Msg: PJJC-1705-7251

From: JBARKER

To: KANDERSON

CC: wbarnes, bguenther, mdking, vsalomonson, rweber

Subj: MODIS Pointing Knowledge Requirement

20 March 1992

To: Ken Anderson/EOS-PM MODIS/422

From: John Barker/MCST/925

Subject: MODIS Pointing Knowledge Requirement

Yes, MODIS does require at least 108 arc sec accuracy for the spacecraft component of the pointing knowledge, and in fact, it has been our assumption that with the smaller EOS-AM and EOS-PM platforms that you would be able to further reduce this requirement beyond the 108 arc sec that was dictated to us from the original EOS-A platform people.

The rationale for a requirement of at least 108 arc sec pointing knowledge is summarized in a recent paper by Vince Salomonson and myself entitled "EOS Moderate Resolution Imaging Spectroradiometer: Phase C/D Status and Comments on Calibration and Georeferencing Approaches," which was given as a talk at the 15 Annual AAS Guidance and Control Conference in February 1992. I will send you a copy of this by EMAIL, and I will also send a hardcopy directly through the regular mail.

One of the primary reasons for the requirement is that the between-instrument masking utility products for clouds and land, which will be automatically applied to all MODIS data, and to many of the inputs for products from instruments such as AIRS and MISR, requires geolocation without any reference to ground control points.

We are holding a MODIS Science Team meeting from April 13th through 16th. If you require any specific validation of our requirements, this should be examined during this meeting. We would like to know what you might need to support this platform requirement, if anything.

cc:

Bill Barnes/970

Mike King/913

Barbara Grant/925

Vince Salomonson/900

Bruce Guenther/925

Dick Weber/422

Chris Justice/923



EOS MODERATE RESOLUTION IMAGING
SPECTRORADIOMETER: PHASE C/D STATUS
AND COMMENTS ON CALIBRATION AND
GEOREFERENCING APPROACHES


Vincent V. Salomonson and John L. Barker

15th ANNUAL AAS GUIDANCE AND CONTROL CONFERENCE

February 8-12, 1992
Keystone, Colorado



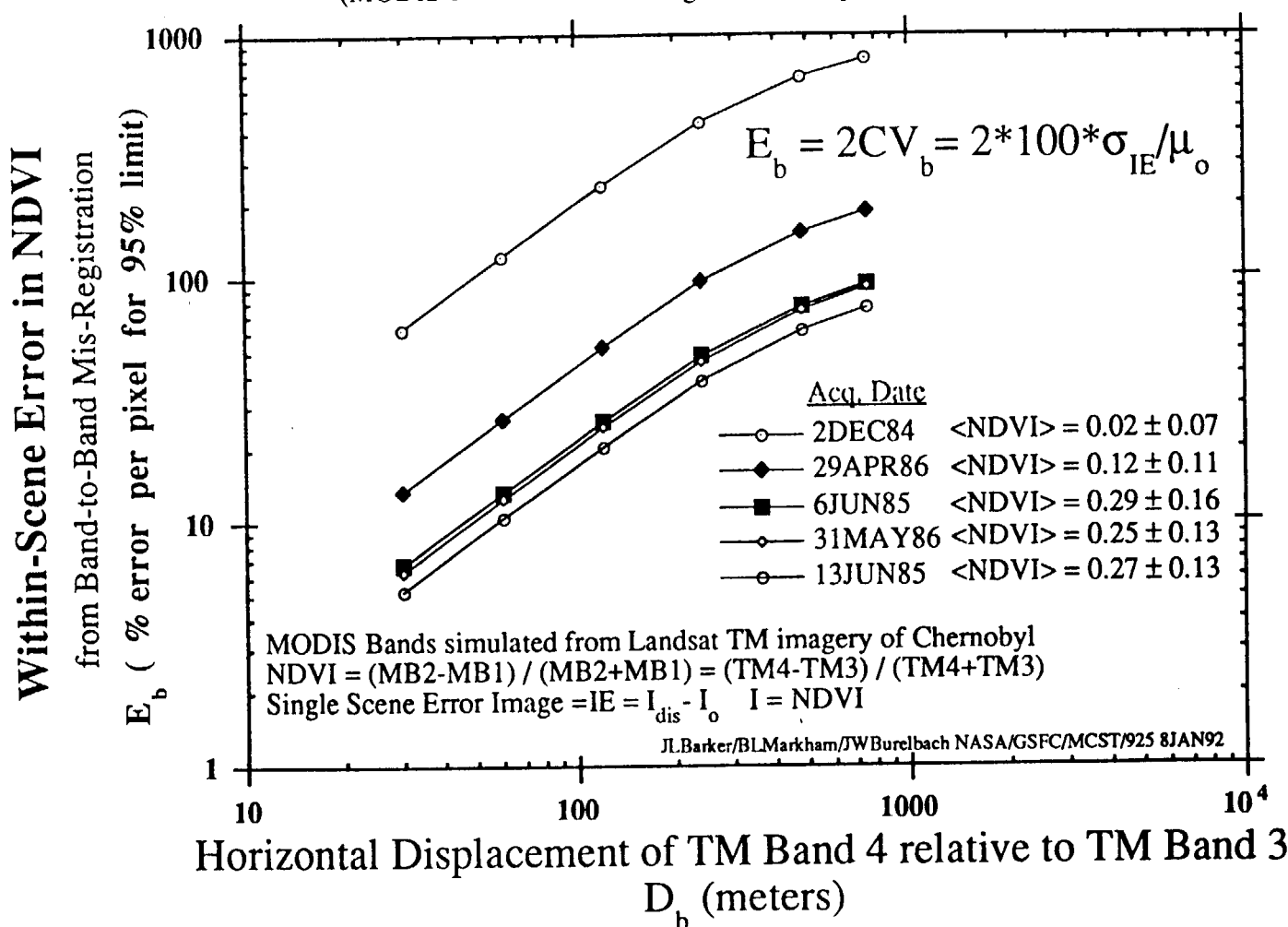
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 PUBLICATIONS OFFICE, P. O. BOX 28130 - SAN DIEGO, CALIFORNIA 92128

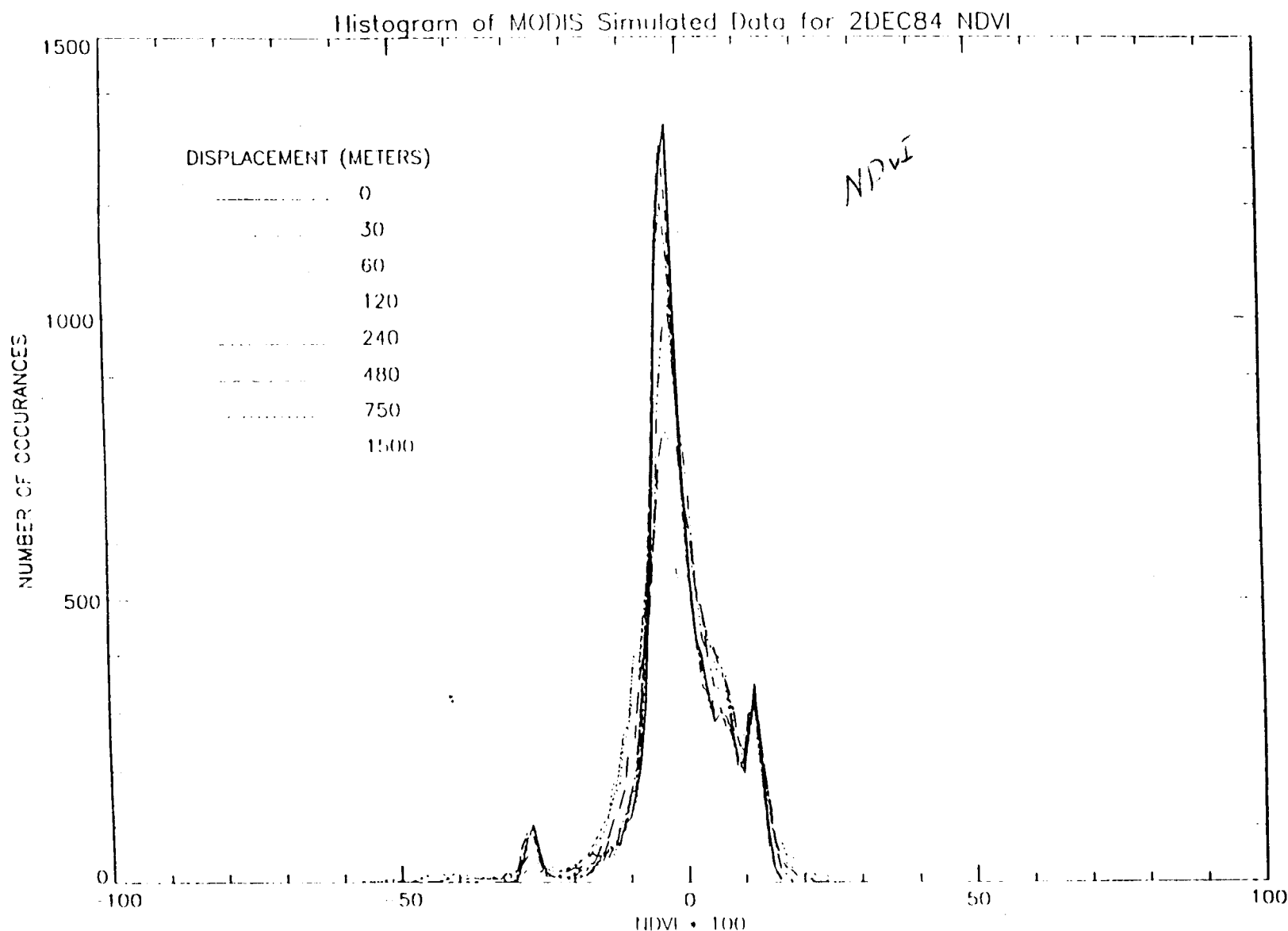
Simulated MODIS-N Sensitivity Studies by MCST

MODIS-N Band-to-Band Registration Sensitivity

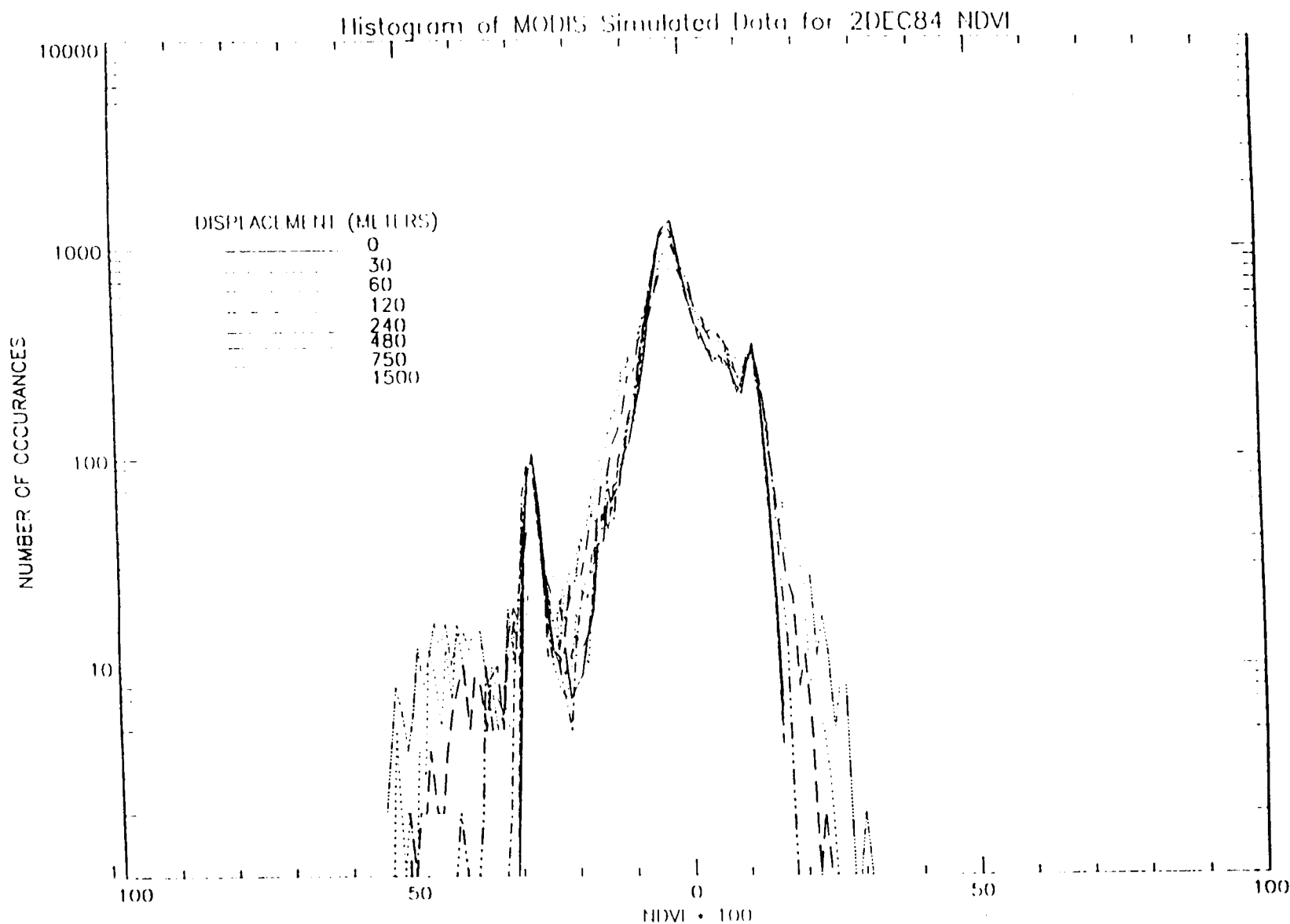
for measuring an NDVI vegetation index over land within a single scene
(MODIS-N Band-to-Band Registration Requirement is 0.1 Pixel)



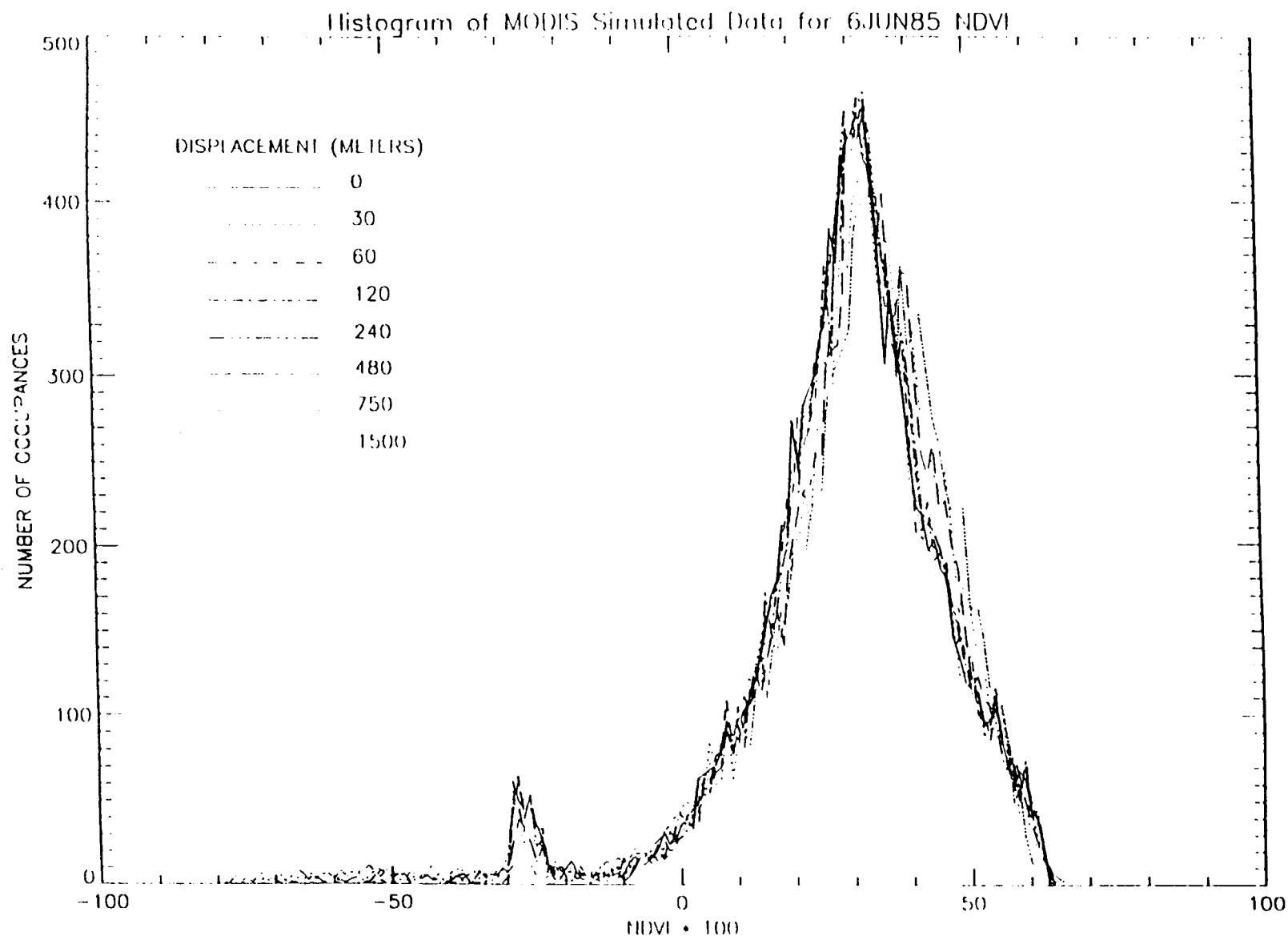
MCST Simulated MODIS Full-Scene Histogram indicating Effects of Band-to-Band Mis-Registration



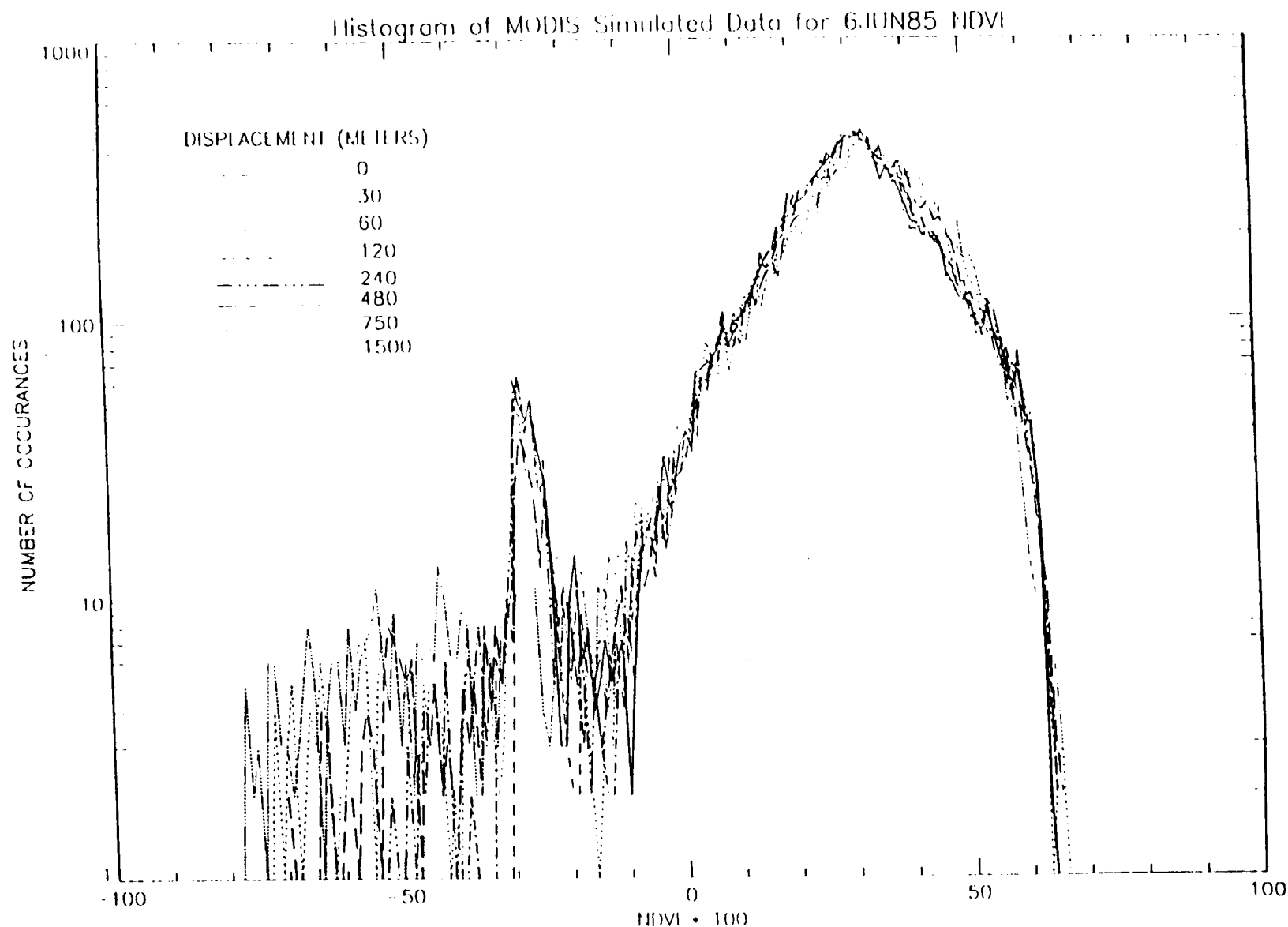
MCST Simulated MODIS Full-Scene Histogram indicating Effects of Band-to-Band Mis-Registration



MCST Simulated MODIS Full-Scene Histogram indicating Effects of Band-to-Band Mis-Registration



MCST Simulated MODIS Full-Scene Histogram indicating Effects of Band-to-Band Mis-Registration

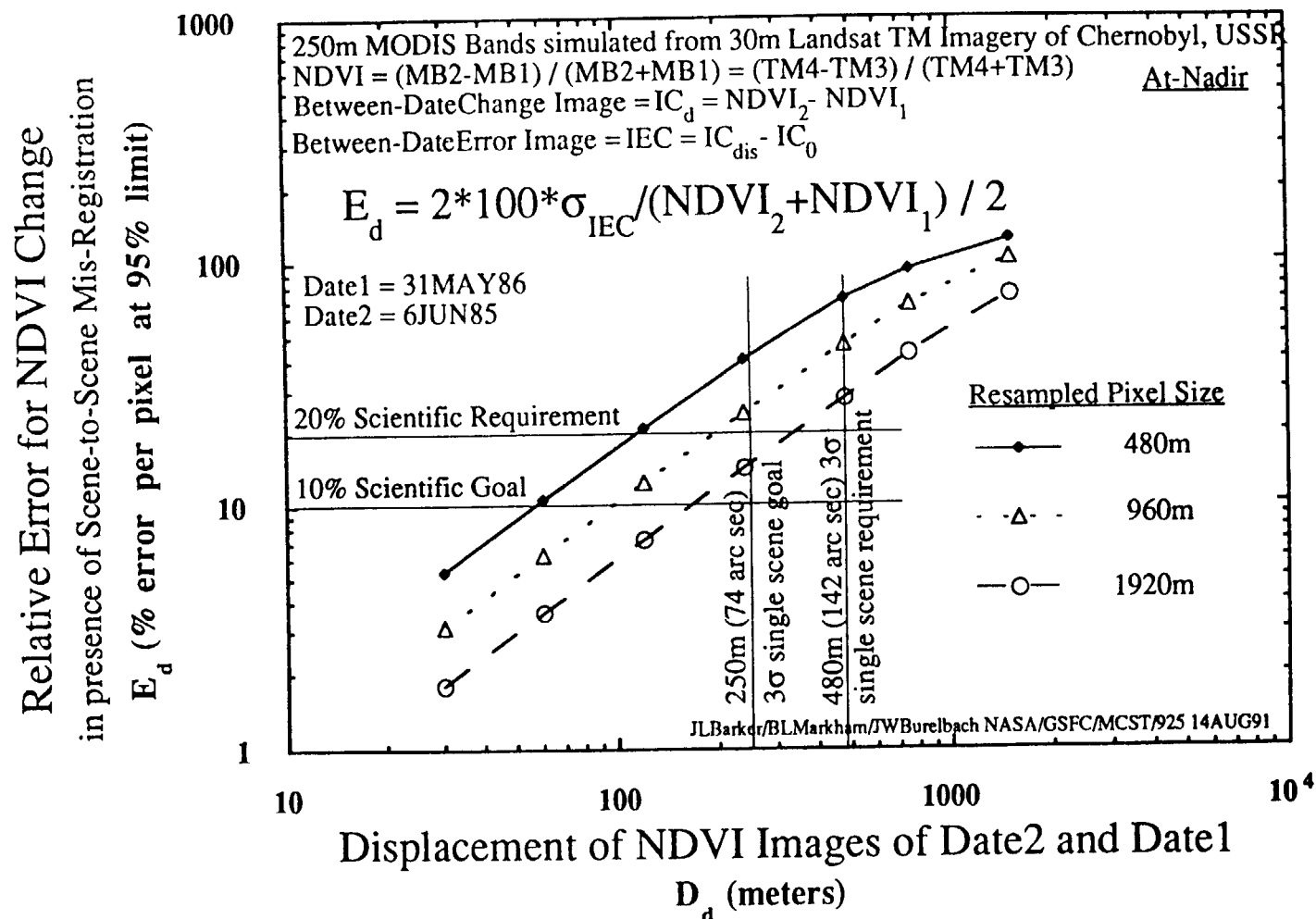


Simulated MODIS-N Sensitivity Studies by MCST

MODIS Scene-to-Scene Registration Sensitivity

for measuring an NDVI vegetation index over land

for examining combined Instrument and Observatory Pointing Knowledge Requirements



MODIS Geometry Requirements Table

from response to GE questionnaire

35

Parameter	Reference Axis	MODIS Instrument Requirement		EOS Observatory Requirement		End-to-End Requirement		RT or PP (Note 1)
Pointing Knowledge		arc seconds	meters at Nadir	arc seconds	meters at Nadir	arc seconds	meters at Nadir	
	x	90	(310)	108 ⁹²	(370)	(141)	(480)	PP (Note 3)
	y	90	(310)	108	(370)	(141)	(480)	PP (Note 3)
	z	90	(310)	108	(370)	(141)	(480)	PP (Note 3)
Pointing Accuracy		arc seconds	meters at Nadir	arc seconds	meters at Nadir	arc seconds	meters at Nadir	
	x	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
	y	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
	z	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
Stability		Arc Seconds per second	Meters per second	Arc Seconds per second	Meters per second	Arc Seconds per second	Meters per second	
	x	(510)	(1740)	(510)	(1750)	720	(2460)	RT
	y	(20)	(70)	(20)	(70)	28	(96)	RT
	z	(20)	(70)	(20)	(70)	720	(2460)	RT

all 15m

Note 1: Specify RT for real-time or PP for post-processed performance.

Note 2: List maximum peak-to-peak excursion in arcseconds and corresponding time period. All periods of interest should be listed. For example, 8 arcseconds in 10 seconds and 15 arcseconds in 500 seconds is the form of the response required.

Note 3: To be available at the same time as Level-0 instrument data.

() Parentheses indicate derived numbers.

MODIS Geometry Goal Table from response to GE questionnaire

Parameter	Reference Axis	MODIS Instrument Goal		EOS Observatory Goal		End-to-End		RT or PP (Note 1)
Pointing Knowledge		arc seconds	meters at Nadir	arc seconds	meters at Nadir	arc seconds	meters at Nadir	
	x	(50)	(175)	(50)	(175)	(73)	250	PP (Note 3)
	y	(50)	(175)	(50)	(175)	(73)	250	PP (Note 3)
	z	(50)	(175)	(50)	(175)	(73)	250	PP (Note 3)
Pointing Accuracy		arc seconds	meters at Nadir	arc seconds	meters at Nadir	arc seconds	meters at Nadir	
	x	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
	y	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
	z	(2550)	(8700)	(2550)	(8700)	3600	(12000)	RT
Stability		Arc Seconds per second	Meters per second	Arc Seconds per second	Meters per second	Arc Seconds per second	Meters per second	
	x	TBD	TBD	TBD	TBD	TBD	TBD	RT
	y	TBD	TBD	TBD	TBD	TBD	TBD	RT
	z	TBD	TBD	TBD	TBD	TBD	TBD	RT

Note 1: Specify RT for real-time or PP for post-processed performance.

Note 2: List maximum peak-to-peak excursion in arcseconds and corresponding time period. All periods of interest should be listed. For example, 8 arcseconds in 10 seconds and 15 arcseconds in 500 seconds is the form of the response required.

Note 3: To be available at the same time as Level-0 instrument data.

() Parentheses indicate derived numbers.

Overview of Part 2

of

MCST Presentation to Land Working Group

Land-Related Science Team Objectives

MCST Priorities

MODIS/MCST Utility Data Products

Texture Algorithm

Objectives and Approach

Classification Overlay/Masking Algorithm

Objectives

Phased Development

MCST-Related MODIS Scene Simulation Activities

Requirements, Properties and Approach

Atmospheric Models

Global Site Selection

Simulated MODIS U. S. Land/Water Mask

Suggested MCST Land-Related WG Action

Science Team Objectives and Suggested Land WG Action

1. Re-evaluate selection of science algorithms
as a result of current instrument selection.

Suggested Action:

Need Land WG endorsement of up-dated list of utility products.

2. Report on current status of algorithm development.

Suggested Action:

Indicate utility products are under development

3. Identify the planned level of algorithm development
in light of current budget and time constraints.

Suggested Action:

Confirm 1990/1991 MCST lower priority
for land-related utility products than for calibration-related products

4. Your algorithm development plans and schedule for development.

Suggested Action:

Develop schedule for peer review and delivery of algorithms

5. Your current perception of planned stage of algorithm development
before entrusting to the Science Data Support Team (MSDST)

Suggested Action:

Indicate intent to provide peer-reviewed and working S/W to MSDST

Priority Order of MCST-Related Activities

unchanged from
1990 and 1991 MODIS Science Team Meetings

1. Instrument-Related Characterization/Calibration
2. Algorithms, Software and Hardware
for EOC/MCST Monitoring of In-Orbit Data
3. Utility Products
4. Simulated MODIS Imagery
5. Cooperative Team Member and MCST
Discipline-Related Product Sensitivity to Calibration

At-Launch MODIS Utility Data Products*

MCST Product Generation Responsibilities

Derived Level-2 Imagery

Three level-2 image spatial products, i. e. for sets of 250, 500, and 1000 m bands

Texture Products

Sixteen-Bit Radiometric Spatial Heterogeneity/Texture Image
derived from one or both of the 250 m MODIS bands

One-Bit "Pure Pixel" Binary Mask

Classification Overlay Map

Classification Mask of Homogeneous Areas, including classes for:

"Definitely" Cloud

"Definitely" Not Cloud

"Definitely" Shadow

"Definitely" Not Shadow

"Definitely" Water

"Definitely" Not Water

"Definitely" Snow/Ice

"Definitely" Not Snow/Ice

"Definitely" Vegetation

"Definitely" Not Vegetation

"Definitely" Land

"Definitely" Not Land

Image Terminator Line

Calculated Terminator Line

- * At-launch products will be up-dated after launch
to go from radiance-based to reflectance and temporally-based algorithms,
including extension to critical level-3 products.

MODIS/MCST Land Data Products*

Discipline Group	Parameter :: Qualifier	Investigator	Time	Original Product Name (from Investigator)
LAND	Texture::MODIS Level-2	Salomonson/Barker	AL	Utility Algorithm with Strahler
LAND	Texture::MODIS Level-3	Salomonson/Barker	PL	Utility Algorithm with Strahler
LAND	Classification::MODIS Masks Level-2	Salomonson/Barker	AL	Cloud/Snow/Land/Water Utility Mask with Hall
LAND	Classification::MODIS Masks Level-3	Salomonson/Barker	PL	Cloud/Snow/Land/Water Utility Mask with Hall

- * As currently carried in the EOS Science Data Product Database (Yun Chi Lu/936)
- * The question of whether there are unique EOS-AM, EOS-PM or combined EOS-AM/EOS-PM land data products has not been examined.

Are there any other MODIS Team Members from the Land Discipline who wish to collaborate on the two utility products?

MODIS/MCST Texture Utility Algorithm

Objectives and Approach

Create un-resampled level-2 data products
for the three MODIS spatial resolutions
namely, 250, 500 and 1000 m

Three 16-Bit Texture Products

Develop spatial texture measure using 250m bands

Calculate geophysically based texture measures

perhaps standard deviation of NDVI

Three 1-Bit Texture "Pure Pixel" Masks

Label each pixel as "pure" or mixed

by thresholding of texture product

Classification Overlay/Masking Utility Algorithm Objectives and Priorities

Create un-resampled level-2 data products
as classification overlay masks
for the three MODIS spatial resolutions
namely, 250, 500 and 1000 m

The priority order for mask generation is

1. Clouds
2. Snow/Ice
to provide the input for at-launch snow cover product
3. Water
4. Land, vegetated and non-vegetated
5. Image Terminator Line
both observed by thresholding on imagery
and by calculation of known Sun/Satellite positions
6. Cloud Shadows
calculated from the cloud mask and cloud height

Classification Overlay/Masking Utility Algorithm

Key Elements in Phased Developmental Approach

Pre-Launch Phase

Level-2 Exoatmospheric Reflectance used as Input

Texture Mask to identify Spectral Signatures from "Pure Pixels"

Unsupervised Classification

Post-Launch Phase

Reflectance-Based

after application of MODIS Atmospheric Utility

Directional

Bidirectional

Time-Dependent Classification Use of Prior Classifications

to Change A Priori Probabilities

to Provide Fitting Parameters for Predictive Models

Regional Validation based on ASTER and Landsat TM Imagery

Global Comparison to AVHRR Cover Maps

MCST-Related MODIS Scene Simulation Activities

Requirements for Simulated Data Sets

Simulated data sets are required to develop, characterize and validate :

- Calibration algorithms and trade-off studies

 - for both the instrument and platform

- Science and utility algorithms

 - for information extraction

- Operational software for the processing algorithms

 - for the ground processing/data reduction computers

Simulated data sets can provide only a limited representation

- of the actual temporal data sets

- that will be acquired by the MODIS instruments in space

 - i. e., they are **not** intended for a priori

 - representative characterization of global processes

MCST-Related MODIS Scene Simulation Activities

Desired Properties of the Simulated Data Sets

Be derivable conveniently, cost-effectively and in a timely manner

Cover the spectral, radiometric, geometric, field-of-view, temporal and other operational ranges of the MODIS instruments, including typical or pseudo-realistic cases, and limiting or extreme cases

Be structured for parametric sensitivity studies to readily reveal behavioral characteristics of system under consideration

Allow scene modification/creation for unanticipated needs

Provide for easy validation against well understood existing real datasets (the simulated data **correspondence** principle)

Be complete enough to allow for stressing all pathways in the software

MCST-Related MODIS Scene Simulation Activities

Approach to Simulating Data Sets

Synthetically and theoretically derived structured scenes

- Well defined geometric patterns of pure pixels to facilitate error analysis

- Groups of pixels possessing artificially defined statistical distributions

 - e.g. areas of given mean radiance and deviation

 - with along track gradient, cross track gradient, etc.

- Fractal generated scenes for representative studies

Scenes derived empirically from existing data sets

- Landsat TM, AVHRR, AVARIS, MAS, etc.

UNIX-based PRA shell for simulation activities

- that includes modifiable sections for the

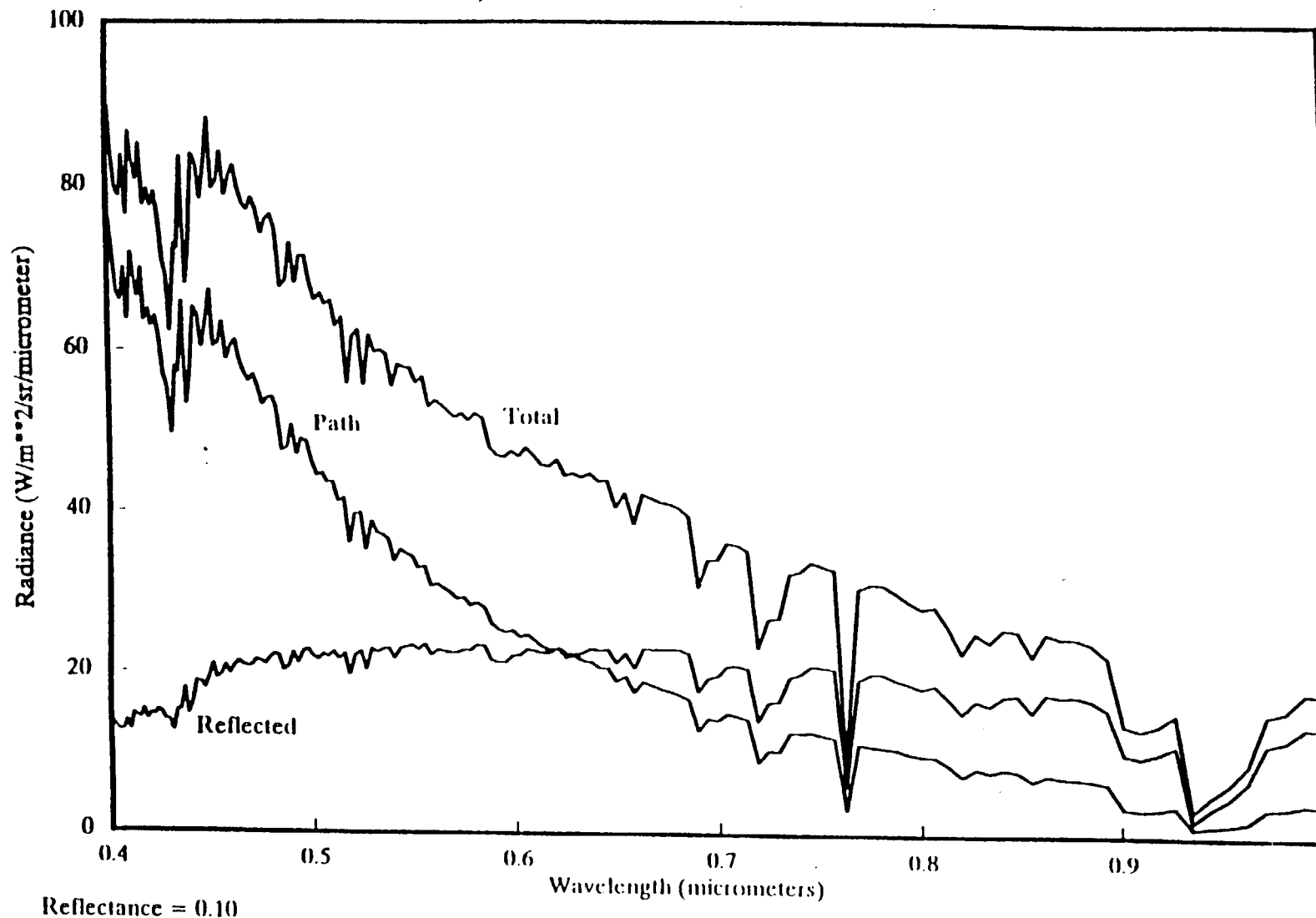
 - source of irradiance

 - scene

 - atmosphere

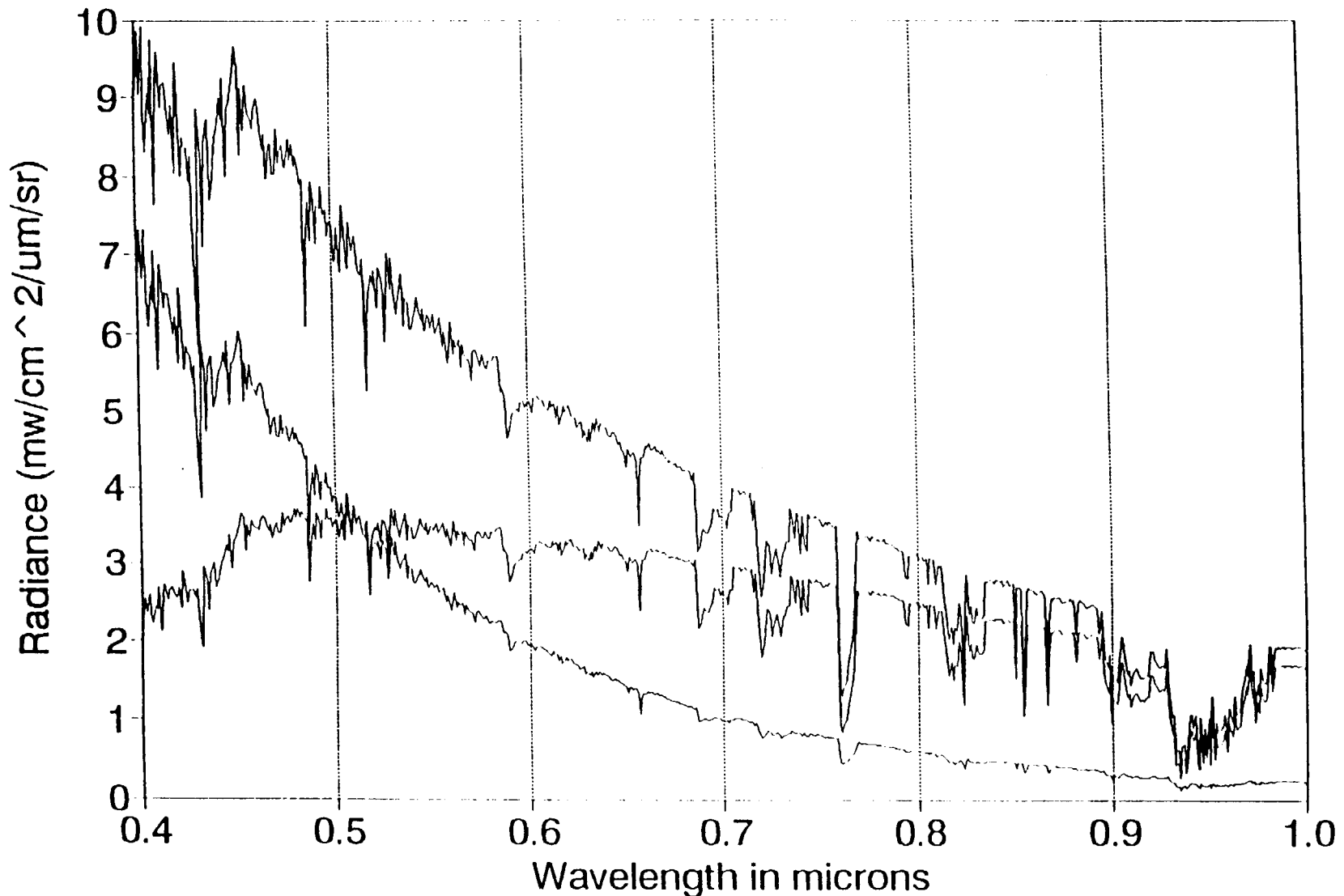
Radiance at Top of Atmosphere from LOWTRAN7 Output--1976 US Standard Atmosphere

23Km Visibility -- 1.125 g/cm**2 Water Vapor
Total, Reflected and Path



Radiance at Top of Atmosphere Derived from MCST Spreadsheet Model

Total, Reflected and Path



Global Calibration Site Selection Procedure

Objective

Locate potential MODIS calibration targets on the Earth's surface that are radiometrically homogeneous on a scale of 3 by 3 Km.

Approach

Initially use annual NDVI biweekly datasets of 1 Km AVHRR data in the continental United States in 1990 to search for radiometrically homogeneous regions using the standard deviation of a traveling 3X3 pixel area as a measure of heterogeneity.

Context

Use calibration sites within the MODIS imagery to provide for

- 1) every-pass calibration potential using a modified "radiometric rectification" methodology,
- 2) aircraft under-flight calibration support, and
- 3) occasional support of ground field calibration experiments

Schedule

Initial results for 1990 dataset from EDC (EROS Data Center) were reported at the Calibration Working Group session of the April 13th MODIS Science Team Meeting

EDC Biweekly AVHRR NDVI Image for Period 6/ 8 to 6/ 21/ 90

